



Astra™ Machina™ SL1680 Developer Kit User Guide

PN: 511-001403-01 Rev E

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1. Introduction

The Astra™ Machina™ Foundation Series of evaluation-ready kits enable easy and rapid prototyping for the Synaptics SL-Series of multi-modal embedded processors. A modular design incorporates swappable core compute modules, a common I/O board, and daughter cards for connectivity, debug, and flexible I/O options.

The Synaptics Astra SL-Series is a family of highly integrated AI-native Linux® and Android™ SoCs optimized for multi-modal consumer, enterprise, and industrial IoT workloads with hardware accelerators for edge inferencing, security, graphics, vision, and audio. The SL1680 incorporates high-performance compute engines, including a quad-core Arm® Cortex®-A73 64-bit CPU subsystem, a multi-TOPS NPU, a high-efficiency, feature-rich GPU for advanced graphics and AI acceleration, and multimedia accelerators for image signal processing (ISP), 4K video encode/decode, and audio. The SL1680 SoC brings a combination of performance and feature integration to device manufacturers, enabling multi-modal applications that can meet price points across various IoT market segments.

1.1. Scope

This user guide describes the hardware configuration and functional details for the Astra Machina SL1680 core module, I/O board, and supported daughter cards, in addition to the bring-up sequence for the developer kit.

1.2. Definition of Board Components

- **Astra Machina:** Combined system with core module, I/O board, and supported daughter cards
- **Core module:** Processor subsystem module with key components including SL1680, eMMC, and LPDDR4x.
- **I/O board:** Common base board that includes various standard hardware interfaces, buttons, headers, and power-in.
- **Daughter card:** Add-on boards for supporting various features such as connectivity, debug, and other flexible I/O options.

1.3. Astra Machina System Overview

This section covers system features, block diagrams and top views of the Astra Machina developer kit.

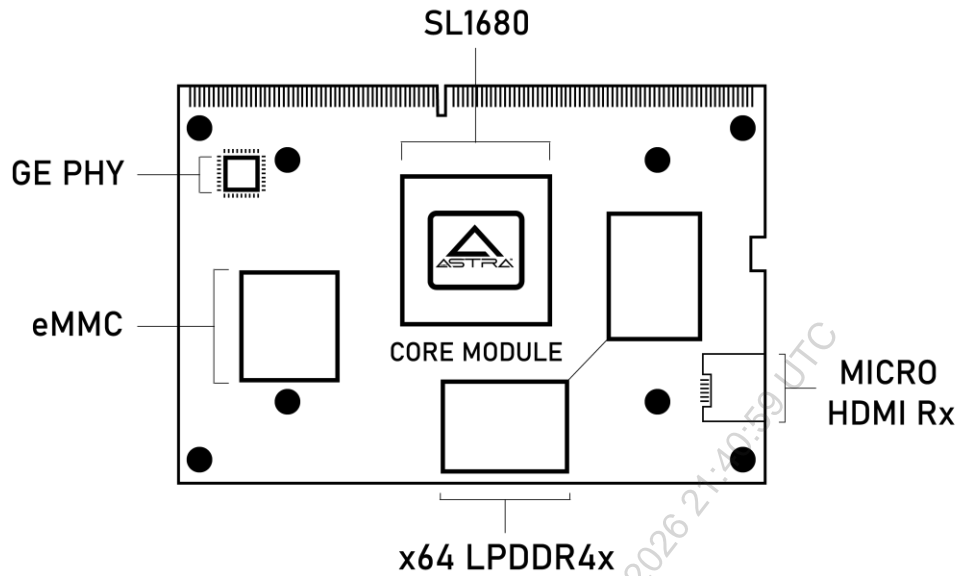


Figure 1. SL1680 core module (Dimensions: WxH = 69.6 x 47.38mm)

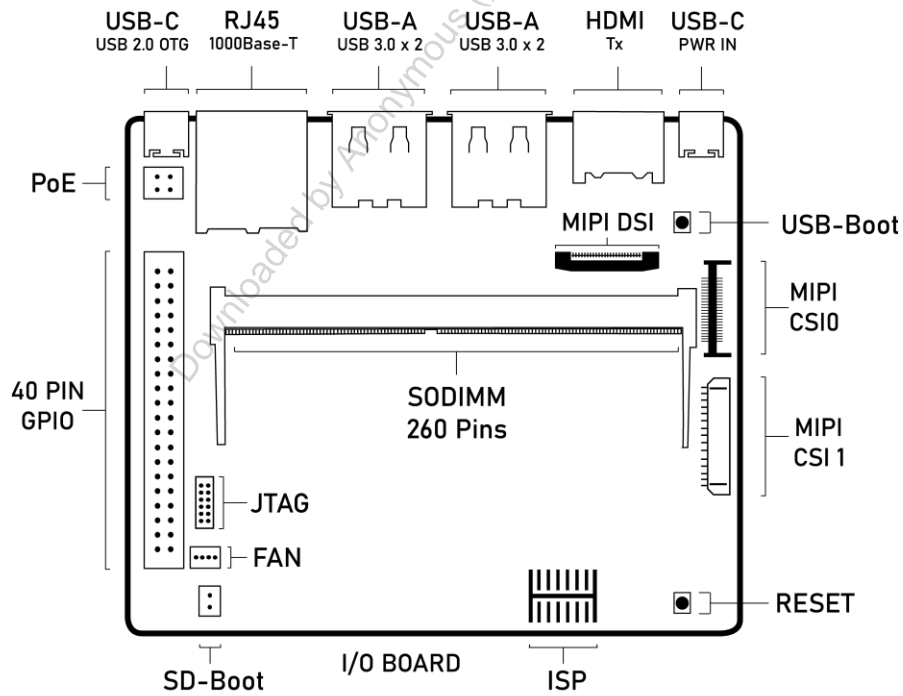


Figure 2. I/O board (Dimensions: WxH = 3937 x 3110mm)

1.3.1. Features

The SL1680-based developer kit includes the following components:

- Main components on the core module:
 - Synaptics SL1680 Quad-Core Arm® Cortex®-A73 embedded IoT processor, up to 2.1 GHz
 - Storage: eMMC 5.1 (32 GB¹)
 - DRAM: up to x64 4 GB system memory by 2pcs x32 16 Gbit LPDDR4x
 - PMIC: two support DVFS in Vcore and Vcpu supply rails
 - HDMI Micro Rx interface: V2.1 with HDCP 2.2 sinks up to 4K60p video and advanced audio
 - SD Card Receptacle
- Main components on the I/O board:
 - HDMI Type-A Tx interface: V2.1 with HDCP 2.2 sources up to 4K60p video and advanced audio
 - M.2 E-key 2230 Receptacle: It supports SDIO, PCIe, UART for Wi-Fi/BT modules
 - USB 3.0 Type-A: 4 ports to support host mode at SuperSpeed.
 - USB 2.0 Type-C: supports OTG host or peripheral mode at Hi-Speed.
 - Push buttons: used for USB-BOOT selection and system RESET.
 - 2pin Header: used for SD-BOOT selection.
- Daughter card interface options:
 - MIPI DSI on 22-pin FPC interface to support 4-lane DSI plus I2C and GPIOs for up to 4K30p/2K60p display panel.
 - MIPI CSI-2 on two FPC interfaces. 22-pin at CSIO for 4-lane, 15pin at CSI1 for 2-lane. Each plus I2C and GPIOs, for up to 4K60p (one camera) or 4K30p (two cameras)
 - JTAG daughter card for debug.
 - 40-pin header for additional functions
 - 4-pin PoE+ connector, with a PoE hat board (purchased separately), it offers an add-on voltage regulator module for PoE+ Type2 (802.3at) power device. Available power shall be 25.5W (Class 4) at 5V pins of 40-pin header to I/O board.
 - 4-pin connector for active Fan with PWM.
- Type-C power supply with 15V@1.8A.

¹Capacity may vary.

1.3.2. SL1680 system block diagram

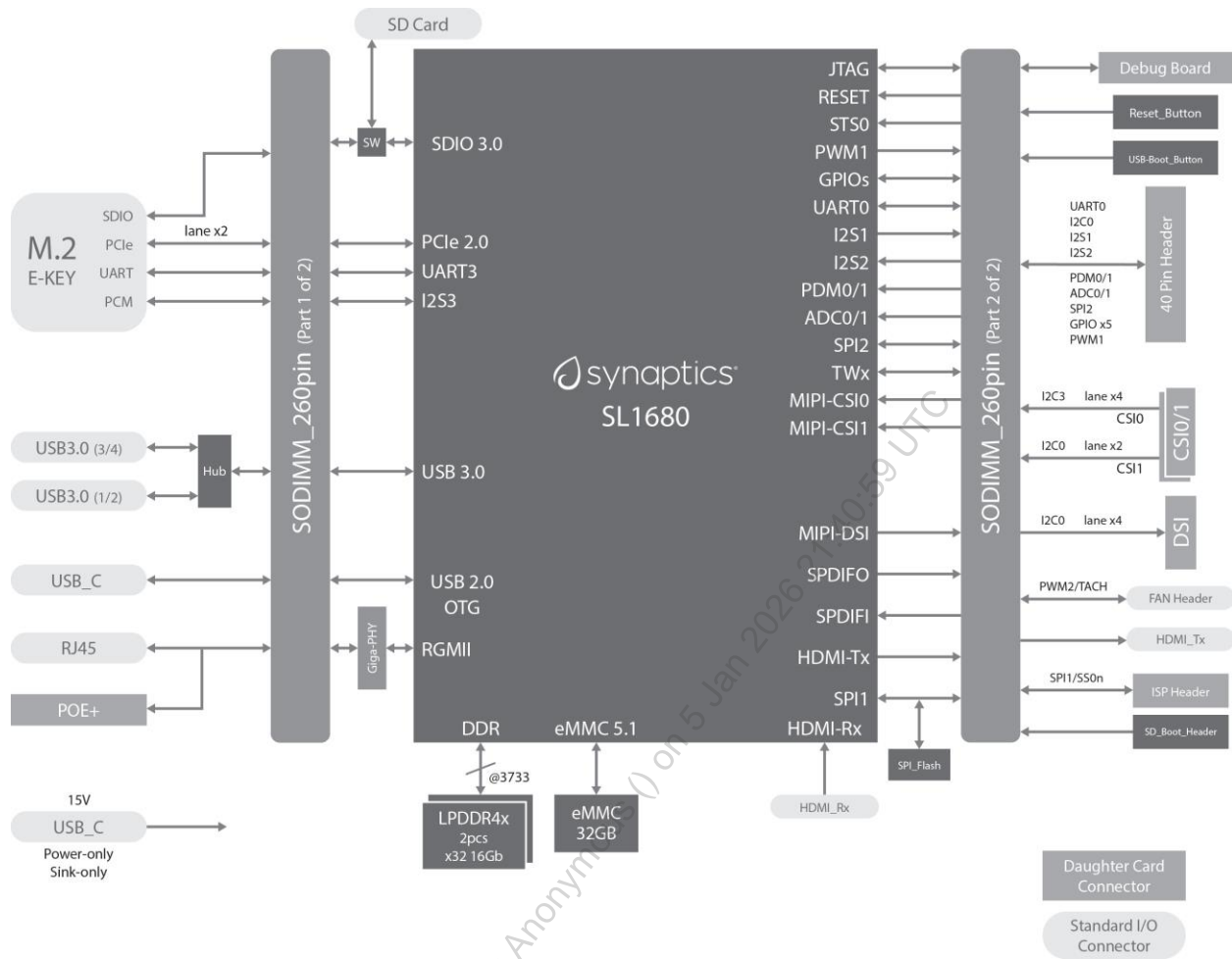


Figure 3. SL1680 system block diagram

1.3.3. Top view of SL1680 Astra Machina developer kit

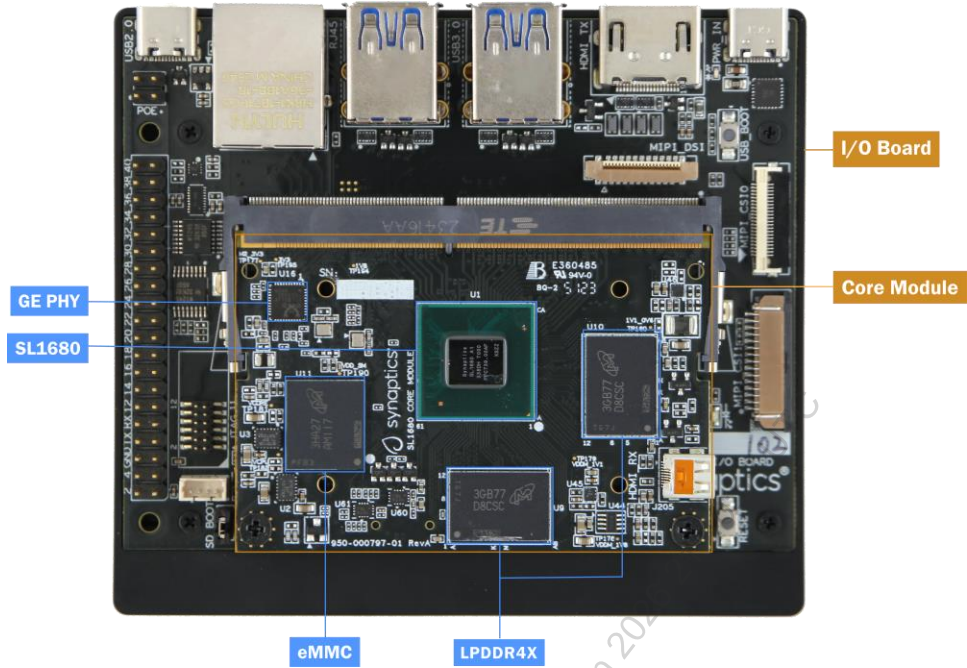


Figure 4. Top view of SL1680 developer kit

1.3.4. System connectors

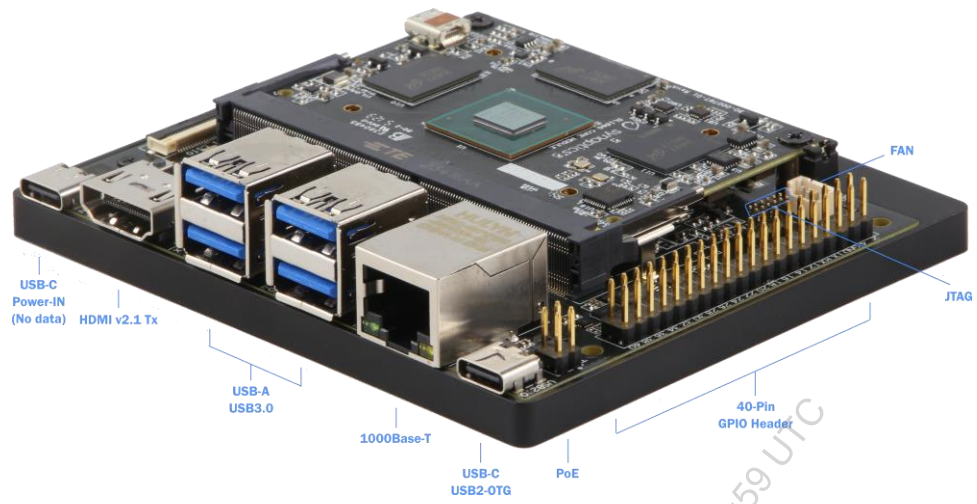


Figure 5. Front view

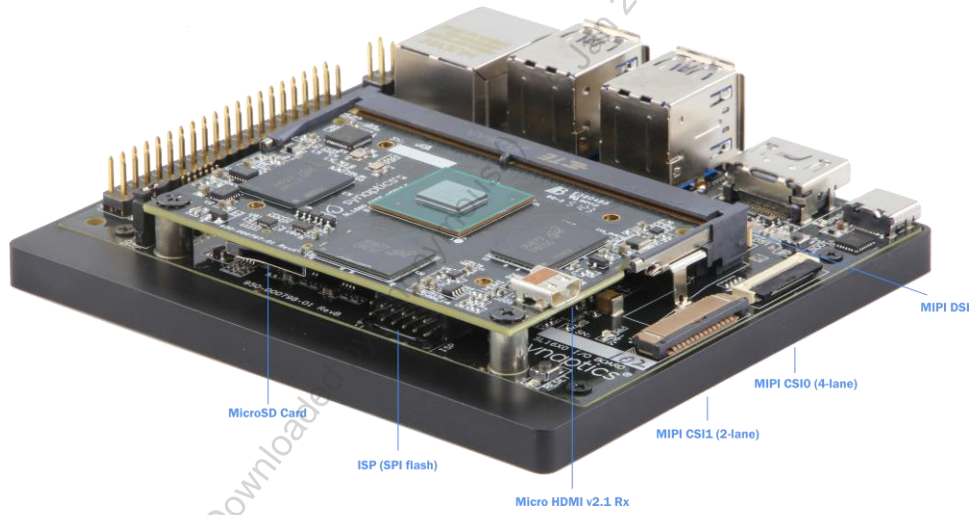


Figure 6. Rear view

2. Astra Machina Board Control/Status & System I/O

This section covers boot-up, LEDs status indicators, buttons, connectors, and pin-strap settings.

2.1. Booting Up

The Astra Machina supports booting from three interfaces. Users can select a boot interface before powering up, as follows: –

- **eMMC boot:** Default boot interface
- **SD boot:** Short SD_Boot header by 2.54mm jumper-cap before power-up, see SD_Boot header in [Figure 9](#). Ensure SD-Card with firmware is plugged into SD-slot on core module in [Figure 11](#).
- **USB boot:** Connect USB-C usb2.0 port to the host PC, then follow the procedure in section [2.5](#).

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2.2. LEDs

2.2.1. LED locations

Figure 7 shows the LED locations on the I/O board.

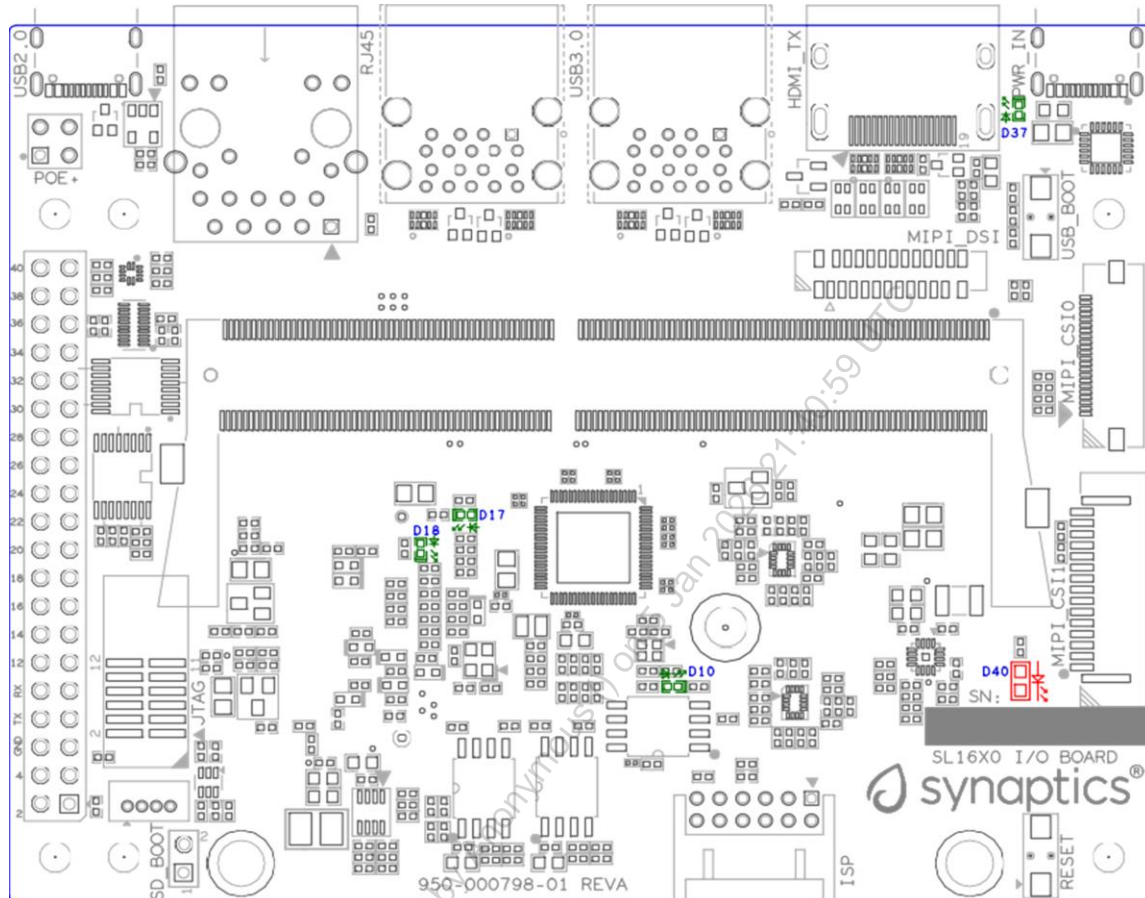


Figure 7. LED locations on I/O board

2.2.2. LED definitions

Table 1. LED definitions on I/O board

LED	Color	LEDs Function
D10	Green	LED indicator for USB3.0 Hub is working in normal mode or suspend mode.
D17	Green	LED indicator1 for M.2 device general purpose.
D18	Green	LED indicator2 for M.2 device general purpose.
D37	Green	LED indicator for Power-on status.
D40	RED	LED indicator for Stand-By Status.

2.3. System Manager (SM) PinStrap and Boot-up Settings

Table 2. SM pinstrap and boot-up settings on core module

Pad Name	Strap Name	Setting Value Default*	Resistor Stuffing + stuffed - removed	Description Rpu = OnChip Pull-up Rpd = OnChip Pull-down
SM_URTO_TXD	SM_STRP[0]	—	—	SM to SoC RSTn mode select (Rpd)
		0*	-R188	0: socRstN releasing waits for SoCRstCnt but does not wait for SM_PWR_OK (mode_0 of SM_URTO_TXD, system will assert this signal when SoC core power is ready).
		1	+R188	1: socRstN releasing waits for both SoCRstCnt and SM_PWR_OK.
SM_SPI2_SDO	SM_STRP[1]	—	—	Straps for software usage (Rpd)
		0*	-R190	—
		1	+R190	—
SM_SPI2_SSOIn	SM_STRP[2]	—	—	Straps for software usage (Rpd)
		0*	-R192	—
		1	+R192	—
SM_SPI2_SSIn	SM_STRP[3]	—	—	Straps for software usage (Rpd)
		0*	-R194	—
		1	+R194	—
SM_TEST_EN	SM_TEST_EN	—	—	SM TEST Enable (Rpd)
		0*	-R184	0: Enable ARM ICE JTAG connections (CoreSight)
		1	+R184	1: Enable SCAN or BSCAN tests
SM_JTAG_SEL	SM_JTAG_SEL	—	—	SM JTAG Port Selection (Rpd)
		0*	-R186	0: ARM ICE JTAG connections
		1	+R186	1: Reserved for factory use
SM_POR_EN	SM_POR_EN	—	—	Power-on reset (POR) bypass (Rpu)
		0	+R3	0: Bypass on-chip POR generator
		1*	-R3	1: Enable on-chip POR generator

2.4. SoC PinStrap and Boot-up Settings

Table 3. SoC pinstrap and boot-up settings on core module

Pad Name	Strap Name	Setting Value Default*	Resistor Stuffing + stuffed - removed	Description Rpu = OnChip Pull-up Rpd = OnChip Pull-down
RGMII_TXD[2]	cpuRstByps	—	—	CPU reset bypass strap (Rpd)
		0*	-R178	0: Enable reset logic inside CPU partition
		1	+R178	1: Bypass reset logic inside CPU partition
RGMII_TXD[3]	pllPwrDown	—	—	SYS/MEM/CPU PLL Power Down; Note: pllPwrDown should be set to 1 only when pllByps is also set to 1. (Rpd)
		0*	-R180	0: Power up
		1	+R180	1: Power down
RGMII_TXCTL	pllByps	—	—	SYS/MEM/CPU PLL bypass indicator
		0*	-R182	0: No bypass
		1	+R182	1: All PLL bypassed
SPI1_SSON	software_strap[1]	—	—	Straps for software usage (Rpd)
		0*	-R174	—
		1	+R174	—
RGMII_TXD[0]	software_strap[2]	—	—	Straps for software usage (Rpd)
		0*	-R172	—
		1	+R172	—
RGMII_TXD[1]	software_strap[3]	—	—	Straps for software usage (Rpd)
		0*	-R170	—
		1	+R170	—
SPDIFO	boot_src[1]	—	—	CPU Boot Source bit [1] (Rpu) See boot_src [1:0]
		0	—	ROM boot from SPI.
		1*	—	ROM boot from eMMC.
RGMII_TXC	Legacy_boot	—	—	Strap to reduce reset wait time (Rpd)
		0*	-R176	0: 2 ms
		1	+R176	1: 20 ms

Table 4. Boot-up settings on I/O board

Net Name	Strap Name	Setting Value Default*	Resistor Stuffing + stuffed - removed	Description Rpu = OnChip Pull-up Rpd = OnChip Pull-down
USB_BOOTn	USB-Boot	—	—	ROM code uses this strap to determine if booting from USB or not (Rpu)
		0	—	0: Boot from USB when USB-BOOT button is pressed while system reset de-assertion.
		1*	—	1: Boot from the device select by boot_src[1]
CONN-SPI.VDDIO1P8.BOOT_SRC1	SD-Boot	—	—	ROM code uses this strap to determine if booting from SD_Card or not (Rpu)
		0	—	0: Boot from SD_Card when SD_Boot header is on while system reset de-assertion.
		1*	—	1: Boot from the device select by boot_src[1] when SD_Boot Header is off.

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2.5. Hardware Manual Button Settings

Table 5. Hardware manual button settings definitions on I/O board

Switch Block	Type	Setting	Function
SW6 (RESET)	Momentary Pushbutton	Push	SL1680 Reset Key asserted.
		Release	Key de-asserted.
SW7(USB_BOOT)	Momentary Pushbutton	Push	USB boot Key asserted. Needs combo RESET button. Read below steps on how to enter USB-Boot mode.
		Release	Key de-asserted.

To enter USB-Boot mode, follow these steps:

Note: Prior to these steps, make sure the USB driver is installed successfully on the PC host side. For details, please reference the *Astra SDK Linux User Guide* available on the Synaptics GitHub.

1. Push RESET button to assert system reset to SL1680.
2. Keep pushing RESET button and push USB_BOOT button at the same time for 1-2 seconds.
3. Release RESET button while holding USB_BOOT button, so SL1680 enters USB-Boot mode.
4. Check and wait for the console print... messages.

Once the console print is returned and entered USB boot successfully, release USB_BOOT button.

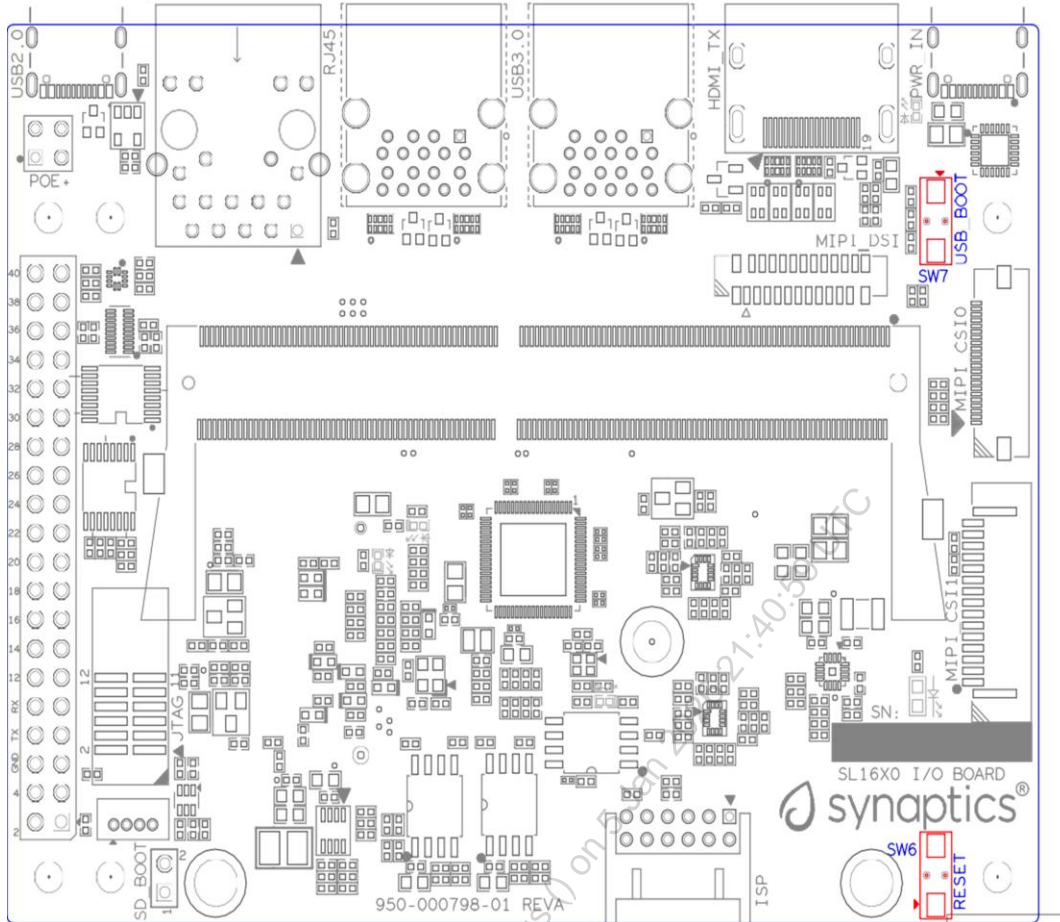


Figure 8. Locations of manual buttons on I/O board

2.6. Hardware Jumper Settings

Table 6. Hardware jumper settings definitions on I/O board

Ref Des	Type	Pin Connection	Description
JP1	2x1 2.54mm header	1-2	SD_Boot selection
			<ul style="list-style-type: none"> Open: Boot from the device select by boot_src[1] Short: Boot from SD_Card while power-up or system reset de-assertion
JP2	2x1 2mm header	1-2	5V_SEL selection
			<ul style="list-style-type: none"> Open: 15V from USB-C adapter Power-In Short: 5V from USB-C adapter Power-In

To enter SD-Boot mode, follow these steps:

Note: Prior to these steps, make sure SD-Card with firmware is plugged into SD-slot on the core module.

1. Short SD_Boot header by 2.54mm jumper-cap before power-up.
2. Power-up system, then boot-up from SD_Card.

Figure 9 shows the Header locations on the I/O board.

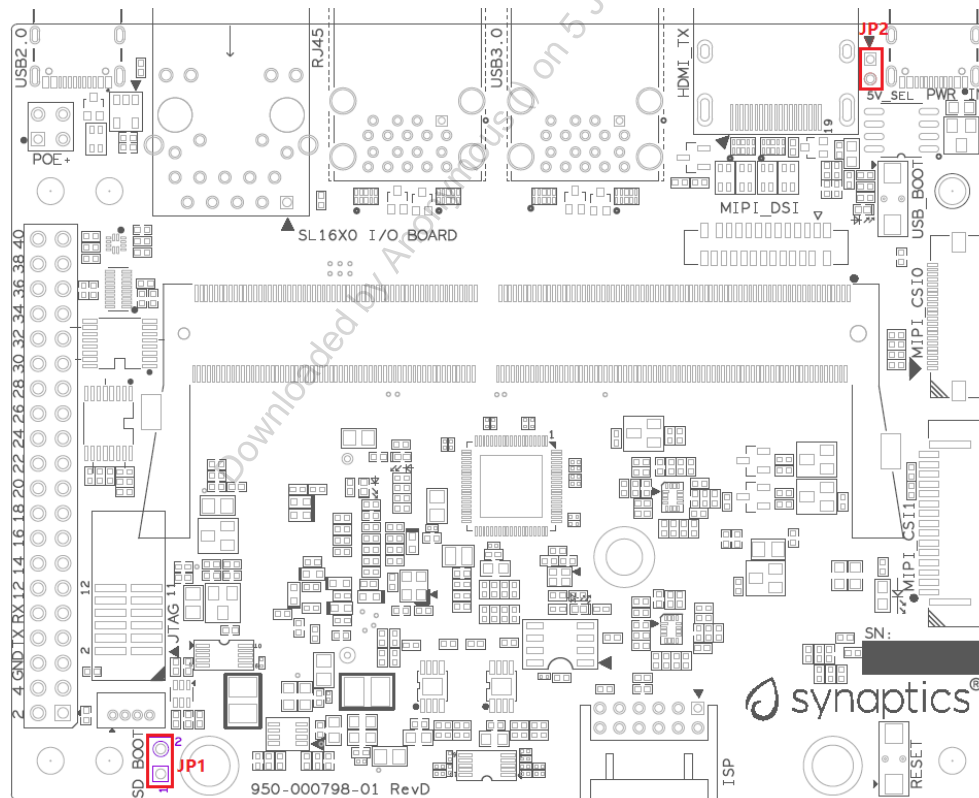


Figure 9. Locations of jumpers on the I/O board

2.7. SL1680 Developer Kit Connectors

2.7.1. Location of connector on the top side of the core module

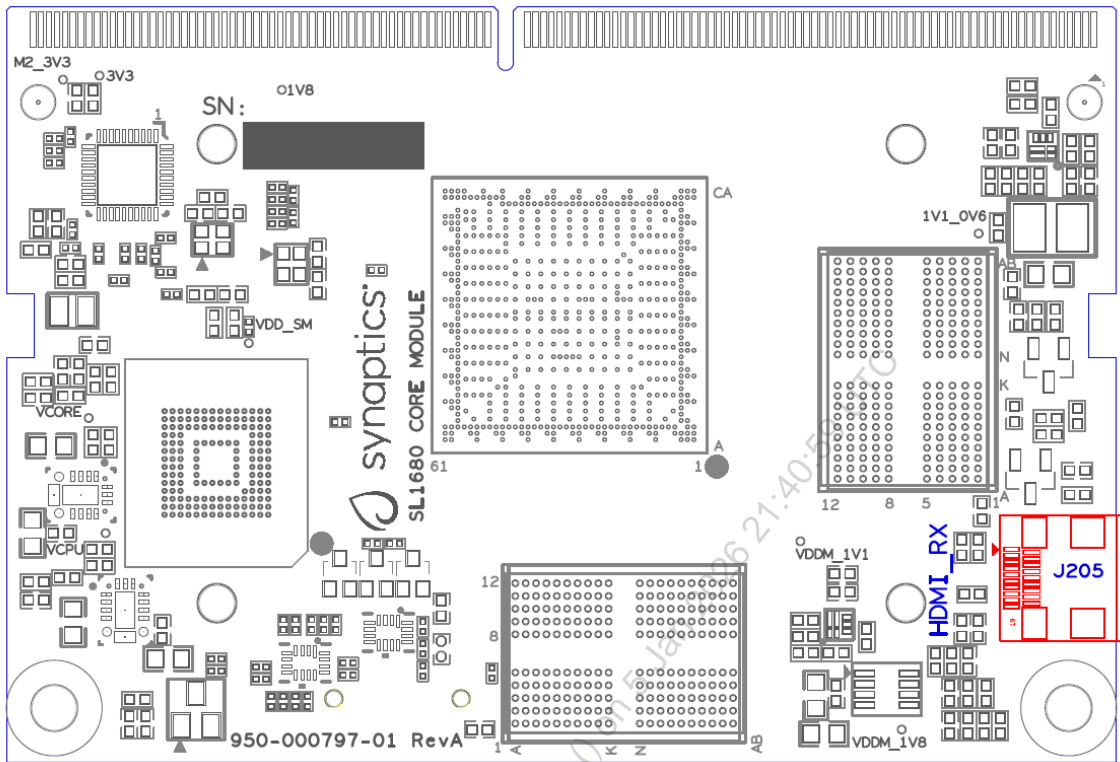


Figure 10. Location of connector on the top side of the core module

2.7.2. Location of connector on the bottom side of the core module

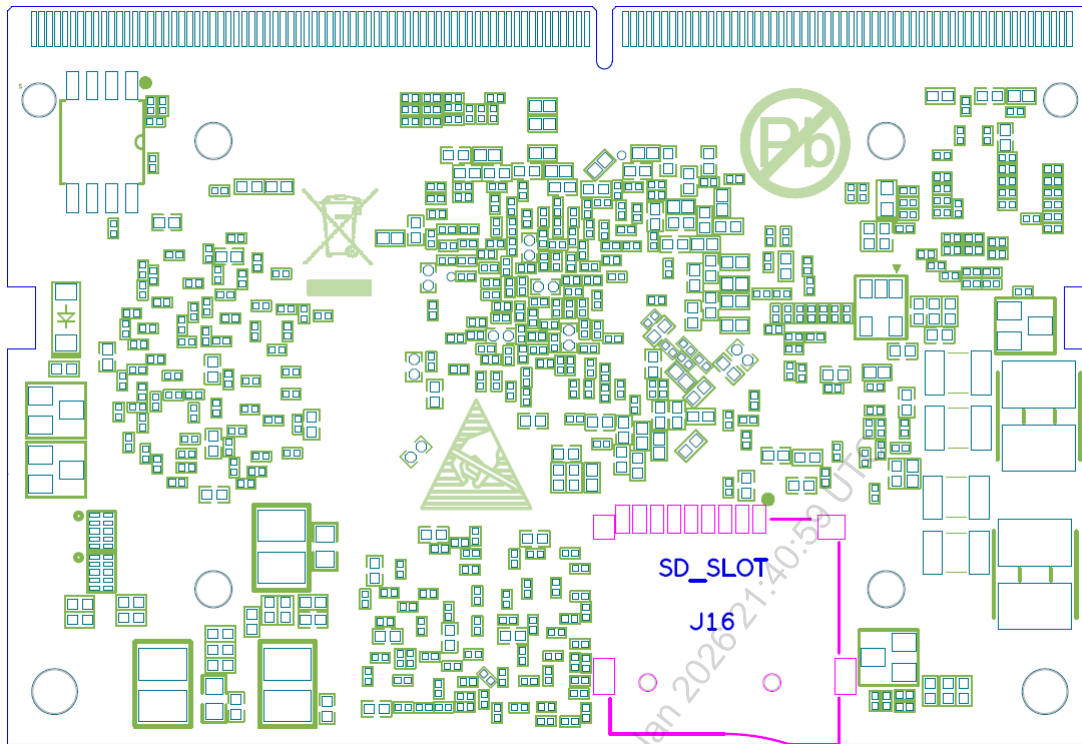


Figure 11. Location of connector on the bottom side of the core module

2.7.3. Core module connector definitions

Table 7. Core module connector definitions

Main Ref Des	Connecting Boards/Devices (Ref Des if any)	Functions	Remarks
J205	HDMI Sink	HDMI_Rx	For off-board HDMI source host connection.
J16	MicroSD Card	SDIO card	For micro-SD type of memory card extension.

2.7.4. Locations of connectors on the top side of the I/O board

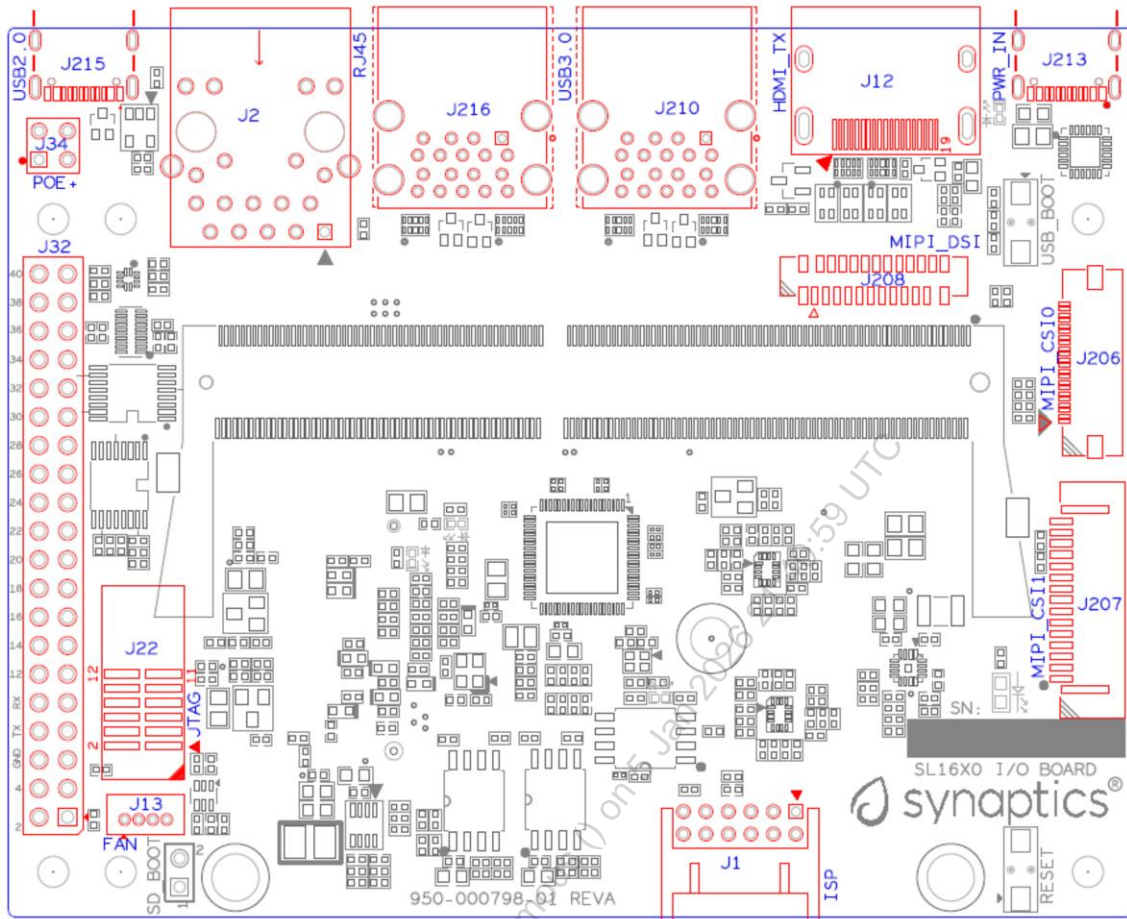


Figure 12. Locations of connectors on the top side of the I/O board

2.7.6. I/O board connector definitions

Table 8. I/O board connector definitions

Main Ref Des	Connecting Boards/Devices (Ref Des if any)	Functions	Remarks
J1	ISP D/C	SPI	12-pin daughter card to support offline program SPI NOR flash on core module
J2	RJ45 cable	Giga Ethernet	For Wired Ethernet connection
J12	HDMI Sink	HDMI TX	For off-board HDMI Sink device connection
J13	FAN	Heat Dissipation w/ FAN	Active FAN with PWM
J17	M.2 2230 D/C	SDIO and PCIe	1x1/2x2 WiFi/Bluetooth card via SDIO or PCIe
J22	Debug Board	JTAG	XDB debugger for debugging
J32	40-pins Header	Uart,I2C,SPI,PDM,I2SI/O, GPIOs,STS1,PWM,ADC	Flexible for support various D/C
J34	PoE+ D/C	PoE+	4-pin PoE+ daughter card with supporting an add-on 5V voltage to 40pin Header.
J206	MIPI-CSIO adaptor	MIPI-CSI	For MIPI-CSI x4 lane extension, like camera
J207	MIPI-CSI1 adaptor	MIPI-CSI	For MIPI-CSI x2 lane extension, like camera
J208	MIPI-DSI adaptor	MIPI-DSI	For MIPI-DSI x4 lane extension, like panel
J210	USB Device	USB 3.0 x2	For USB3.0 extension in Device mode only
J213	TypeC power source	Power Supply	Power for Astra Machina rated at 15V/1.8A
J215	USB Device	USB2.0 OTG	For USB2.0 extension, in either Host or Device mode
J216	USB Device	USB 3.0 x2	For USB3.0 extension in Device mode only

3. Daughter Cards

A set of daughter cards supplements the Astra Machina system with a range of extensible and configurable functionalities including Wi-Fi and Bluetooth connectivity, debug options and general purpose I/O. Details of currently supported daughter cards are described in this section.

3.1. Debug Board

Debug Board (Rev5) allows users to communicate with the SL1680 system over JTAG through a Debugger on a PC host. While connecting the Astra Machina and debug board with a 20-pin flat cable, align pin-1 of the 2x10 cable socket at the debug board side with pin-1 of 2x6 header J22 on the developer kit.

Users may communicate with SL1680 over UART on a PC host by using a UART to USB cable commonly available. See the Astra Machina webpage for a list of qualified parts. As an option, the debug board also provides such bridging function based on the Silicon Labs CP2102. A virtual COM port driver is required, and can be downloaded from the following link and installed on the host PC: <https://www.silabs.com/products/development-tools/software/usb-to-uart-bridge-vcp-drivers>

UART on the developer kit and the PC host USB are digitally isolated, with no direct conductive path, eliminating ground loop and back-drive issues when either is powered down.

Figure 14 shows debug board connectivity facilitating UART and JTAG communications.

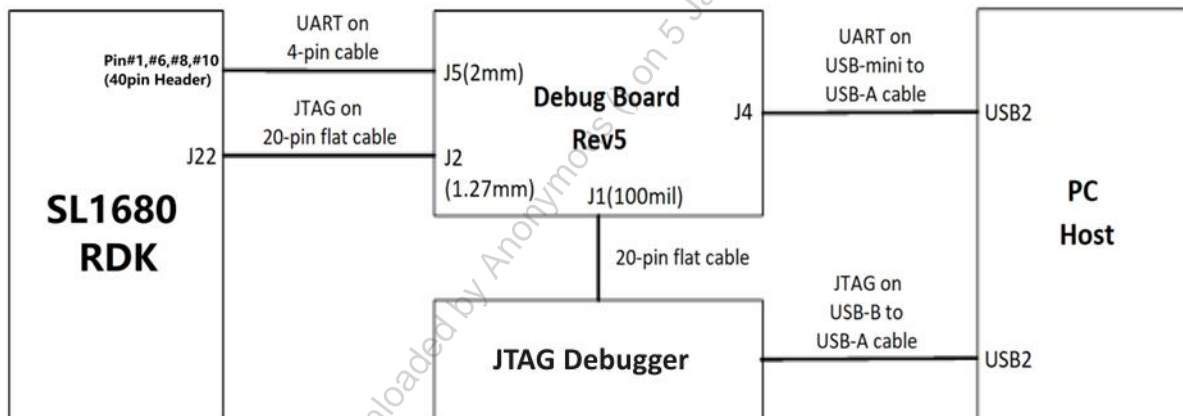


Figure 14. Debug board connectivity for UART and JTAG

3.2. M.2 Card

An M.2 E-Key socket J17 is provided for a variety of modules in the M.2 form factor. Typical applicable modules support Wi-Fi/BT devices with SDIO or PCIE signal interfaces.

Available modules:

- Ampak AP12275_M2P with SYN43752 2x2 WiFi6/BT5.3 2x2 over PCIE on M.2 adaptor
- Ampak AP12276_M2P with SYN43756 2x2 WiFi6E/BT5.3 2x2 over PCIE on M.2 adaptor

3.3. 260-Pins SODIMM Definition

A 260-Pins SODIMM connector (PN: TE_2309413-1) joins the core module and the I/O board. [Table 9](#) shows the assignment for the 260-Pins.

Table 9. 260-Pins SODIMM definition

Assignment	Pin#	260-Pins SODIMM	Pin#	Assignment
VDDM_LPQ_control (From IO_Exp)	2		1	N.A
SPI1_SDO (USB_BOOTn)	4		3	N.A
SPI1_SCLK	6		5	N.A
VDDM_control (From IO_Exp)	8		7	N.A
HDMI_RX.V3P3.CEC	10		9	N.A
SPI1_SDI	12		11	N.A
SPI1_SSO _n	14		13	N.A
External_Boot_SRCO	16		15	N.A
N.A	18		17	N.A
N.A	20		19	N.A
N.A	22		21	N.A
N.A	24		23	N.A
GND	26		25	N.A
MIPI_CS11_RD0 _p	28		27	N.A
MIPI_CS11_RD0 _n	30		29	N.A
GND	32		31	N.A
MIPI_CS11_RD1 _n	34		33	N.A
MIPI_CS11_RD1 _p	36		35	N.A
GND	38		37	N.A
MIPI_CS11_RCK _p	40		39	N.A
MIPI_CS11_RCK _n	42		41	N.A
GND	44		43	N.A
USB2_D _n	46		45	N.A
USB2_D _p	48		47	N.A
GND	50		49	N.A
USB3_RX _p	52		51	N.A
USB3_RX _n	54		53	GND
GND	56		55	MIPI_CSIO_RD2 _n
USB3_TX _p	58		57	MIPI_CSIO_RD2 _p
USB3_TX _n	60		59	GND
GND	62		61	MIPI_CSIO_RD3 _n
USB3_USB20.D _p	64		63	MIPI_CSIO_RD3 _p

Assignment	Pin#	260-Pins SODIMM	Pin#	Assignment
USB3_USB20.Dn	66		65	GND
GND	68		67	MIPI_CSIO_RD1p
USB2_IDPIN	70		69	MIPI_CSIO_RD1n
PWR_OTG_VBUS	72		71	GND
PWR_USB3_VBUS	74		73	MIPI_CSIO_RD0n
I2S3_BCLK	76		75	MIPI_CSIO_RD0p
I2S3_DI	78		77	GND
I2S3_DO	80		79	MIPI_CSIO_RCKp
I2S3_LRCK	82		81	MIPI_CSIO_RCKn
I2S2_DI[0]	84		83	GND
PDM_DIO	86		85	PCIe_RX1p
PDM_DI1	88		87	PCIe_RX1n
PDM_CLKO	90		89	GND
I2S2_BCLK	92		91	PCIe_TX1n
I2S2_LRCK	94		93	PCIe_TX1p
GPIO10	96		95	GND
FAN_TACH_Control	98		97	PCIe_RX0p
SPDIFO	100		99	PCIe_RX0n
FAN_PWM	102		101	GND
I2S1_BCLK	104		103	PCIe_TX0n
EXPANDER_INT-REQn	106		105	PCIe_TX0p
BOOT_SRC1	108		107	GND
I2S1_DOO	110		109	PCIe_CLKp
I2S1_MCLK	112		111	PCIe_CLKn
I2S1_LRCK	114		113	GND
ADC1[0]	116		115	MIPI_DSI_TDOn
ADC1[1]	118		117	MIPI_DSI_TDOp
URTO_TXD	120		119	GND
URTO_RXD	122		121	MIPI_DSI_TD1n
SPI2_SDI	124		123	MIPI_DSI_TD1p
SPI2_SCLK	126		125	GND
SPI2_SDO	128		127	MIPI_DSI_TCKp
SPI2_SS3n	130		129	MIPI_DSI_TCKn
USB2_OCn	132		131	GND
SPI2_SS1n	134		133	MIPI_DSI_TD3n
SPI2_SSO n	136		135	MIPI_DSI_TD3p
SM_TW3_SDA	138		137	GND


Assignment	Pin#	260-Pins SODIMM	Pin#	Assignment
SM_TW3_SCL	140		139	MIPI_DSI_TD2p
N.A	142		141	MIPI_DSI_TD2n
N.A	144		143	GND
N.A	146		145	GND
N.A	148		147	HDMI_TX_TCKn
N.A	150		149	HDMI_TX_TCKp
HDMITX_HPD	152		151	GND
USB-C_Logic_INTn	154		153	HDMI_TX_TDOn
HDMI_TX_EDDC_SDA	156		155	HDMI_TX_TDOp
HDMI_TX_EDDC_SCL	158		157	GND
Levershift_EN# for 40P header	160		159	HDMI_TX_TD1n
SM_HDMI_CEC	162		161	HDMI_TX_TD1p
RSTIn@PU	164		163	GND
JTAG_TDO	166		165	HDMI_TX_TD2n
JTAG_TDI.SoC_WakeUp#	168		167	HDMI_TX_TD2p
JTAG_TMS	170		169	GND
N.A	172		171	HDMITX-eARC_RXn
N.A	174		173	HDMITX-eARC_RXp
GPIO39	176		175	GND
TW2B_SDA	178		177	HDMI_TX_PWR_EN
TW2B_SCL	180		179	JTAG_TCK
TWO_SDA	182		181	GPIO38
TWO_SCL	184		183	JTAG_TRSTn
URT3_CTSn for M.2	186		185	GPIO36
URT3_RTSn for M.2	188		187	URT3_RXD for M.2
PWM1	190		189	GPIO37
GND	192		191	URT3_TXD for M.2
PWR_1V8	194		193	N.A
PWR_1V8	196		195	N.A
PWR_1V8_CTL	198		197	N.A
PWR_1V8_CTL	200		199	N.A
PWR_3V3_CTL	202		201	TW1B_SCL
PWR_3V3_CTL	204		203	TW1B_SDA
GND	206		205	USB_BOOTn
M.2_WIFI_SDIO_CLK	208		207	Vcore/Vcpu control (From IO_Exp)
GND	210		209	GePHY_LED1&&STRP[CFG_LDOO]

Assignment	Pin#	260-Pins SODIMM	Pin#	Assignment
M.2_WIFI_SDIO_CMD	212		211	GePHY_LED2&&STRP[CFG_LDO1]
GND	214		213	GND
M.2_WIFI_SDIO_DO	216		215	RJ45_MDIPO
GND	218		217	RJ45_MDINO
M.2_WIFI_SDIO_D1	220		219	GND
GND	222		221	RJ45_MDIP1
M.2_WIFI_SDIO_D2	224		223	RJ45_MDIN1
GND	226		225	GND
M.2_WIFI_SDIO_D3	228		227	RJ45_MDIP2
GND	230		229	RJ45_MDIN2
PWR_3V3-M.2	232		231	GND
PWR_3V3-M.2	234		233	RJ45_MDIP3
PWR_3V3-M.2	236		235	RJ45_MDIN3
PWR_3V3	238		237	GND
PWR_3V3	240		239	N.A
PWR_3V3	242		241	N.A
GND	244		243	GND
GND	246		245	GND
GND	248		247	GND
GND	250		249	GND
PWR_5V	252		251	PWR_5V
PWR_5V	254		253	PWR_5V
PWR_5V	256		255	PWR_5V
PWR_5V	258		257	PWR_5V
PWR_5V	260		259	PWR_5V

3.4. 40-Pin Header

A 40-pin GPIO header with 0.1-inch (2.54mm) pin pitch is on the top edge of the I/O board. Any of the general-purpose 3.3V pins can be configured in software with a variety of alternative functions. For more information, please refer to the *SL1680 Datasheet*.

Note: Pin16/Pin18 are ADCI[0]/[1], the full-scale voltage is 1.2V@max.



SL1680 RDK 40Pin Header Definition					
3.3V	1	■	●	2	5.0V
TW0_SDA	3	●	●	4	5.0V
TW0_SCL	5	●	●	6	GND
PWM[1]	7	●	●	8	UART0_Tx
GND	9	●	●	10	UART0_Rx
I2S2_BCLK	11	●	●	12	GPIO10
I2S2_LRCK	13	●	●	14	GND
I2S2_DI[0]	15	●	●	16	ADCI[0]
3.3V	17	■	●	18	ADCI[1]
SPI2_SDO	19	●	●	20	GND
SPI2_SDI	21	●	●	22	GPIO37
SPI2_CLK	23	●	●	24	SPI2_SS0n
GND	25	●	●	26	SPI2_SS1n
PDMA_CLKIO	27	●	●	28	PDMA_DI[1]
PDMA_DI[0]	29	●	●	30	GND
GPIO39	31	●	●	32	GPIO38
GPIO36	33	●	●	34	GND
I2S1_LRCK	35	●	●	36	SPI2_SS3n
I2S1_MCLK	37	●	●	38	I2S1_BCLK
GND	39	●	●	40	I2S1_DO[0]

Figure 15. 40-Pins header definition

3.5. Pin-demuxing for Standard Interface Configuration

This section covers pin-demuxing configuration for the SL1680 developer kit.

For System Manager (SM), see [Table 10](#).

For System on Chip (SoC), see [Table 11](#).

Table 10. SM Pin-demuxing usage

SL1680 System Manager (SM) Domain				
	Pad/Pin Name	Default Usage	Direction	Mode Setting
SM_TWSI	SM_TW2_SCL	IO:RX_EDID_SCL	OUT	MODE_0
	SM_TW2_SDA	IO:RX_EDID_SDA	IN/OUT	MODE_0
	SM_TW3_SCL	IO:SM_TW3_SCL	OUT	MODE_1
	SM_TW3_SDA	IO:SM_TW3_SDA	IN/OUT	MODE_1
SM_JTAG	SM_TMS	IO:SM_GPIO[6]	IN/OUT	MODE_1
	SM_TDI	IO:SM_GPIO[7]	IN	MODE_1
	SM_TDO	IO:SM_GPO[8]	OUT	MODE_1
SM_UART0/1	SM_URTO_TXD	O:SM_URTO_TXD	OUT	MODE_0
	SM_URTO_RXD	I:SM_URTO_RXD	IN	MODE_0
	SM_URT1_TXD	IO:SM_TW2B_SCL	OUT	MODE_6
	SM_URT1_RXD	IO:SM_TW2B_SDA	IN/OUT	MODE_6
SM_SPI2	SM_SPI2_SSO _n	O:SM_SPI2_SSO _n	OUT	MODE_0
	SM_SPI2_SS1 _n	O:SM_SPI2_SS1 _n	OUT	MODE_1
	SM_SPI2_SS2 _n	IO:SM_GPIO[15]	IN	MODE_2
	SM_SPI2_SS3 _n	O:SM_SPI2_SS3 _n	OUT	MODE_1
	SM_SPI2_SDO	O:SM_SPI2_SDO	OUT	MODE_0
	SM_SPI2_SDI	I:SM_SPI2_SDI	IN	MODE_0
	SM_SPI2_SCLK	O:SM_SPI2_SCLK	OUT	MODE_0
SM_HDMI	SM_HDMI_TX_HPD	IO:SM_GPIO[2]	OUT	MODE_0
	SM_HDMI_CEC	IO:SM_HDMI_CEC	IN/OUT	MODE_1
	SM_HDMI_RX_HPD	IO:SM_GPIO[20]	OUT	MODE_1
	SM_HDMI_RX_PWR5V	I:SM_HDMIRX_PWR5V	IN	MODE_0

Table 11. SoC Pin-demuxing usage

SL1680 System-on-chip (SoC) Domain				
	Pad/Pin Name	Default Usage	Direction	Mode Setting
SDIO	SDIO_CDn	IO:SDIO_CDn	IN	MODE_0
	SDIO_WP	IO:GPIO[44]	OUT	MODE_1
SPI1	SPI1_SS3n	IO:TWIB_SDA	IN/OUT	MODE_3
	SPI1_SS2n	IO:TWIB_SCL	OUT	MODE_3
	SPI1_SS1n	O:PWM[1]	OUT	MODE_4
	SPI1_SSO n	O:SPI1_SSO n	OUT	MODE_0
	SPI1_SDO	O:SPI1_SDO	OUT	MODE_0
	SPI1_SCLK	O:SPI1_SCLK	OUT	MODE_0
	SPI1_SDI	I:SPI1_SDI	IN	MODE_0
TWO	TWO_SCL	IO:TWO_SCL	OUT	MODE_1
	TWO_SDA	IO:TWO_SDA	IN/OUT	MODE_1
STSO/1	STSO_CLK	I:URT3_RXD	IN	MODE_4
	STSO_SOP	O:URT3_TXD	OUT	MODE_4
	STSO_SD	I:URT3_CTSn	IN	MODE_4
	STSO_VALD	O:URT3_RTSn	OUT	MODE_4
	STS1_CLK	IO:GPIO[39]	IN/OUT	MODE_0
	STS1_SOP	IO:GPIO[38]	IN/OUT	MODE_0
	STS1_SD	IO:GPIO[37]	IN/OUT	MODE_0
	STS1_VALD	IO:GPIO[36]	IN/OUT	MODE_0
USB2	USB2_DRV_VBUS	IO:GPIO[55]	OUT	MODE_1
RGMII	RGMII_MDC	O:RGMII_MDC	OUT	MODE_0
	RGMII_MDIO	IO:RGMII_MDIO	IN/OUT	MODE_0
	RGMII_TXC	O:RGMII_TXC	OUT	MODE_0
	RGMII_TXD[0]	O:RGMII_TXD[0]	OUT	MODE_0
	RGMII_TXD[1]	O:RGMII_TXD[1]	OUT	MODE_0
	RGMII_TXD[2]	O:RGMII_TXD[2]	OUT	MODE_0
	RGMII_TXD[3]	O:RGMII_TXD[3]	OUT	MODE_0
	RGMII_TXCTL	O:RGMII_TXCTL	OUT	MODE_0
	RGMII_RXC	I:RGMII_RXC	IN	MODE_0
	RGMII_RXD[0]	I:RGMII_RXD[0]	IN	MODE_0
	RGMII_RXD[1]	I:RGMII_RXD[1]	IN	MODE_0
	RGMII_RXD[2]	I:RGMII_RXD[2]	IN	MODE_0

SL1680 System-on-chip (SoC) Domain				
Pad/Pin Name		Default Usage	Direction	Mode Setting
	RGMII_RXD[3]	I:RGMII_RXD[3]	IN	MODE_0
	RGMII_RXCTL	I:RGMII_RXCTL	IN	MODE_0
I2S1	I2S1_MCLK	IO:I2S1_MCLK	OUT	MODE_1
	I2S1_LRCK	IO:I2S1_LRCKIO	IN/OUT	MODE_1
	I2S1_BCLK	IO:I2S1_BCLKIO	IN/OUT	MODE_1
	I2S1_DO[0]	O:I2S1_DO[0]	OUT	MODE_1
	I2S1_DO[1]	IO:GPIO[17]	IN	MODE_0
	I2S1_DO[2]	O:PWM[2]	OUT	MODE_2
	I2S1_DO[3]	IO:GPIO[15]	IN	MODE_0
I2S2	I2S2_MCLK	IO:PDMB_CLKIO	OUT	MODE_2
	I2S2_LRCK	IO:I2S2_LRCKIO	IN/OUT	MODE_1
	I2S2_BCLK	IO:I2S2_BCLKIO	IN/OUT	MODE_1
	I2S2_DI[0]	I:I2S2_DI[0]	IN	MODE_1
	I2S2_DI[1]	IO:GPIO[10]	IN/OUT	MODE_0
	I2S2_DI[2]	I:PDMA_DI[1]	IN	MODE_2
	I2S2_DI[3]	I:PDMA_DI[0]	IN	MODE_2
I2S3	I2S3_LRCK	IO:I2S3_LRCKIO	IN/OUT	MODE_1
	I2S3_BCLK	IO:I2S3_BCLKIO	IN/OUT	MODE_1
	I2S3_DI	I:I2S3_DI	IN	MODE_1
	I2S3_DO	O:I2S3_DO	OUT	MODE_1
SPDIF	SPDIFO	O:SPDIFO	OUT	MODE_1
	SPDIFI	IO:GPIO[4]	IN	MODE_0
HDMI_TX_EDDC	HDMI_TX_EDDC_SCL	IO:TX_EDDC_SCL	OUT	MODE_0
	HDMI_TX_EDDC_SDA	IO:TX_EDDC_SDA	IN/OUT	MODE_0

3.6. Pin-demuxing for GPIO/GPO Configuration

This section covers pin-demuxed GPIO/GPO usage of SM (Table 12) and SoC (Table 13) domains.

Table 12. SM GPIO/GPO usage

SL1680 SM GPIO/GPO	Availability	Direction	Default Function	GPIO Signaling
SM_GPIO [0]	Not Available	OUT	IO:RX_EDID_SCL	—
SM_GPIO [1]	Not Available	IN/OUT	IO:RX_EDID_SDA	—
SM_GPIO [2]	MODE_0	OUT	HDMI-RX_HPDMUTE#	0: Assertion MUTE for HDMI-RX HPD 1: De-assertion to align PWR_5V status
SM_GPIO [3]	Not Available	IN/OUT	SM_HDMI_CEC	—
SM_GPIO [4]	Not Available	OUT	IO:SM_TW2B_SCL	—
SM_GPIO [5]	Not Available	IN/OUT	IO:SM_TW2B_SDA	—
SM_GPIO [6]	MODE_1	IN/OUT	Not Assigned	—
SM_GPIO [7]	MODE_1	IN	GePHY_WAKE#	0: Triggered Wakeup from M.2 and GE 1: Idle
SM_GPO [8]	MODE_1	OUT	GePHY_RST#	0: De-assertion 1: Assertion Reset for GE PHY IC
SM_GPIO [9]	Not Available	OUT	IO:SM_TW3_SCL	—
SM_GPIO [10]	Not Available	IN/OUT	IO:SM_TW3_SDA	—
SM_GPIO [11]	MODE_0	OUT	O:SM_SPI2_SCLK	—
SM_GPIO [12]	MODE_0	IN	I:SM_SPI2_SDI	—
SM_GPO [13]	MODE_0	OUT	O:SM_SPI2_SDO	—
SM_GPIO [14]	MODE_1	OUT	O:SM_SPI2_SS3n	—
SM_GPO [15]	MODE_2	IN	USB2_Ocn	0: Assertion for Over-Current on USB2.0 Connector 1: Idle
SM_GPO [16]	MODE_1	OUT	O:SM_SPI2_SS1n	—
SM_GPO [17]	MODE_0	OUT	O:SM_SPI2_SS0n	—
SM_GPIO [18]	Not Available	IN	I:SM_URTO_RXD	—
SM_GPO [19]	Not Available	OUT	O:SM_URTO_TXD	—
SM_GPIO [20]	MODE_1	OUT	Level shifter enable for 40pin Header	0: Enable 1: Disable
SM_GPIO [21]	Not Available	IN	I:SM_HDMIRX_PWR5V	—

Table 13. SoC GPIO/GPO Usage

SL1680 SoC GPIO/GPO	Availability	Direction	Default Function	GPIO Signaling
SOC_GPIO[0]	Not Available	IN	I:I2S3_DI	M.2 I2S_DI
SOC_GPIO[1]	Not Available	OUT	O:I2S3_DO	M.2 I2S_DO
SOC_GPIO[2]	Not Available	IN/OUT	IO:I2S3_BCLKIO	M.2 I2S_BCLK
SOC_GPIO[3]	Not Available	IN/OUT	IO:I2S3_LRCKIO	M.2 I2S_LRCLK
SOC_GPIO[4]	MODE_0	IN	FAN_TACH_CON	0: Error
				1: Normal
SOC_GPIO[5]	Not Available	IN/OUT	IO:TX_EDDC_SDA	—
SOC_GPIO[6]	Not Available	OUT	IO:TX_EDDC_SCL	—
SOC_GPO[7]	MODE_2	OUT	IO:PDMB_CLKIO	To 40Pin Header
SOC_GPIO[8]	MODE_2	IN	I:PDMA_DI[0]	To 40Pin Header
SOC_GPIO[9]	MODE_2	IN	I:PDMA_DI[1]	To 40Pin Header
SOC_GPIO[10]	MODE_0	IN/OUT	IO:GPIO[10]	To 40Pin Header
SOC_GPIO[11]	MODE_1	IN	I:I2S2_DI[0]	To 40Pin Header
SOC_GPIO[12]	MODE_1	IN/OUT	IO:I2S2_BCLKIO	To 40Pin Header
SOC_GPIO[13]	MODE_1	IN/OUT	IO:I2S2_LRCKIO	To 40Pin Header
SOC_GPIO[14]	Not Available	OUT	O:SPDIFO	In reserved
SOC_GPIO[15]	MODE_0	IN	USB-C-Logic_INTn	0: USB2.0 host mode
				1: USB2.0 device mode
SOC_GPIO[16]	MODE_2	OUT	O:PWM[2]	PWM for FAN
SOC_GPIO[17]	MODE_0	IN	EXT-GPIO_INTR#	0: Triggered interrupt from GPIO Expander
				1: Idle
SOC_GPIO[18]	MODE_1	OUT	IO:I2S1_MCLK	To 40Pin Header
SOC_GPO[19]	MODE_1	OUT	O:I2S1_DO[0]	To 40Pin Header
SOC_GPIO[20]	MODE_1	IN/OUT	IO:I2S1_BCLKIO	To 40Pin Header
SOC_GPIO[21]	MODE_1	IN/OUT	IO:I2S1_LRCKIO	To 40Pin Header
SOC_GPO[22]	Not Available	OUT	O:RGMIITXCTL	—
SOC_GPO[23]	Not Available	OUT	O:RGMIITXC	—
SOC_GPO[24]	Not Available	OUT	O:RGMIITXD[3]	—
SOC_GPO[25]	Not Available	OUT	O:RGMIITXD[2]	—
SOC_GPO[26]	Not Available	OUT	O:RGMIITXD[1]	—
SOC_GPO[27]	Not Available	OUT	O:RGMIITXD[0]	—
SOC_GPIO[28]	Not Available	IN/OUT	IO:RGMIIMDIO	—

SL1680 SoC GPIO/GPO	Availability	Direction	Default Function	GPIO Signaling
SOC_GPIO[29]	Not Available	OUT	O:RGMII_MDC	—
SOC_GPIO[30]	Not Available	IN	I:RGMII_RXCTL	—
SOC_GPIO[31]	Not Available	IN	I:RGMII_RXC	—
SOC_GPIO[32]	Not Available	IN	I:RGMII_RXD[3]	—
SOC_GPIO[33]	Not Available	IN	I:RGMII_RXD[2]	—
SOC_GPIO[34]	Not Available	IN	I:RGMII_RXD[1]	—
SOC_GPIO[35]	Not Available	IN	I:RGMII_RXD[0]	—
SOC_GPIO[36]	MODE_0	IN/OUT	IO:GPIO[36]	To 40Pin Header
SOC_GPIO[37]	MODE_0	IN/OUT	IO:GPIO[37]	To 40Pin Header
SOC_GPIO[38]	MODE_0	IN/OUT	IO:GPIO[38]	To 40Pin Header
SOC_GPIO[39]	MODE_0	IN/OUT	IO:GPIO[39]	To 40Pin Header
SOC_GPIO[40]	Not Available	OUT	O:URT3_RTSn	For M.2 URT3_RTSn
SOC_GPIO[41]	Not Available	IN	I:URT3_CTSn	For M.2 URT3_CTSn
SOC_GPIO[42]	Not Available	OUT	O:URT3_TXD	For M.2 URT3_TXD
SOC_GPIO[43]	Not Available	IN	I:URT3_RXD	For M.2 URT3_RXD
SOC_GPIO[44]	MODE_1	OUT	MicroSD_PWR_ON	O: Power Down I: Power Up
SOC_GPIO[45]	Not Available	IN	IO:SDIO_CDn	—
SOC_GPIO[46]	Not Available	IN/OUT	IO:TWO_SDA	—
SOC_GPIO[47]	Not Available	OUT	IO:TWO_SCL	—
SOC_GPIO[48]	Not Available	IN	I:SPI1_SDI	—
SOC_GPIO[49]	Not Available	OUT	O:SPI1_SCLK	—
SOC_GPO[50]	Not Available	OUT	O:SPI1_SDO	—
SOC_GPIO[51]	Not Available	IN/OUT	IO:TW1B_SDA	—
SOC_GPIO[52]	Not Available	OUT	IO:TW1B_SCL	—
SOC_GPIO[53]	MODE_4	OUT	O:PWM[1]	To 40Pin Header
SOC_GPO[54]	Not Available	OUT	O:SPI1_SSn	—
SOC_GPIO[55]	MODE_1	OUT	HDMI-TX_PWR_ON	O: Power Down HDMI-TX 5V I: Power Up

3.7. GPIO Expanders Over I2C

Due to the considerable number of functionalities covered by the SL1680 developer kit, most of the SL1680 digital pins that have GPIO/GPO pin-demux options are used for other functions. As such, GPIO expanders are used extensively to supplement system control purposes.

Table 14. GPIO expanders usage

Expander GPIO/GPO	I2C#	Domain	Voltage	Direction	Function	GPIO Signaling
GPIO0_0	SM_TW3 (0x43)	SM	3.3	OUT	VCPU/VCORE_ON#	0: Power ON VCPU/VCORE PMIC 1: Power OFF
GPIO0_1	SM_TW3 (0x43)	SM	3.3	OUT	PWR_ON_DSI	0: Power OFF 1: Power ON
GPIO0_2	SM_TW3 (0x43)	SM	3.3	OUT	VDDM_ON#	0: Power ON all VDDM PMICs (1V8/1V1/OV6) 1: Power OFF
GPIO0_3	SM_TW3 (0x43)	SM	3.3	OUT	VDDM-LPQ_OFF#	0: Power ON VDDM-LP PMICs (OV6) 1: Power OFF
GPIO0_4	SM_TW3 (0x43)	SM	3.3	OUT	STAND-BY_EN	0: Normal status 1: Entry to Stand-By status with devices Powered down
GPIO0_5	SM_TW3 (0x43)	SM	3.3	OUT	USB2.0_PWR_EN	0: Power OFF 1: Power ON
GPIO0_6	SM_TW3 (0x43)	SM	3.3	IN	M2-PCIe_CLKREQ#	0: Triggered for M.2 PCIe Clock Request 1: Idle
GPIO0_7	SM_TW3 (0x43)	SM	3.3	IN/OUT	GPIO_DSI	In reserved In reserved
GPIO1_0	SM_TW3 (0x44)	SM	3.3V	IN/OUT	GPIO_CSIO	In reserved In reserved
GPIO1_1	SM_TW3 (0x44)	SM	3.3V	OUT	M2-PCIe_RST#	0: Assertion Reset for M.2 PCIe Module 1: De-assertion
GPIO1_2	SM_TW3 (0x44)	SM	3.3V	OUT	M2-W_DISABLE1#	0: Assertion Disable to M.2 module by DISABLE1# 1: De-assertion

Expander GPIO/GPO	I2C#	Domain	Voltage	Direction	Function	GPIO Signaling
GPIO1_3	SM_TW3 (0x44)	SM	3.3V	OUT	M2-W_HOST-WAKE#	0: Assertion Wake from Host to M.2 module
						1: De-assertion
GPIO1_4	SM_TW3 (0x44)	SM	3.3V	OUT	PWR_ON_CSIO	0: Power OFF
						1: Power ON
GPIO1_5	SM_TW3 (0x44)	SM	3.3V	OUT	M2-W_DISABLE2#	0: Assertion Disable to M.2 module by DISABLE2#
						1: De-assertion
GPIO1_6	SM_TW3 (0x44)	SM	3.3V	IN/OUT	GPIO_CSII	In reserved
						In reserved
GPIO1_7	SM_TW3 (0x44)	SM	3.3V	OUT	PWR_ON_CSII	0: Power OFF
						1: Power ON

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3.8. I2C Bus

This section describes the Astra Machina's usage of the I²C bus, the equivalence of SL1680's Two Wire Serial Interface (TWSI) bus.

Table 15. I2C bus descriptions

I2C/TWSI Bus	Device	Part Number	Ref Des	Target Address (7-bit)	Location
SM_TW3	Current monitor for PWR_3V3	INA220	U76	0x40	SL16x0 I/O board
	Current monitor for PWR_1V8	INA220	U77	0x41	SL16x0 I/O board
	IC GPIO EXPANDER I2C 8Bit	FXL6408UMX	U12	0x43	SL16x0 I/O board
	IC GPIO EXPANDER I2C 8Bit	FXL6408UMX	U13	0x44	SL16x0 I/O board
	External device connects to MIPI_CSIO connector	Not applicable	J206	0xXX	SL16x0 I/O board
SM_TW2B	IC REG, default 0.8V Vout /5mV Step, 6A rating, Input 6V@Max, Step-Down Convertor with I2C	TPS62870Y1QWRXSRQ1	U3	0x40	SL1680 core module
SOC_TWIB	IC REG, default 0.8V Vout /5mV Step, 6A rating, Input 6V@Max, Step-Down Convertor with I2C	TPS62870Y1QWRXSRQ1	U2	0x40	SL1680 core module
SOC_TWO	External device connects to MIPI_CSII connector	Not applicable	J207	0xXX	SL16x0 I/O board
	External device connects to MIPI_DSI connector	Not applicable	J208	0xXX	SL16x0 I/O board
	External device connects to 40pin Header	Not applicable	J32	0xXX	SL16x0 I/O board
	Current monitor for Vcore, Vcpu, VDDM_1V1	INA3221	U75	0x40	SL1680 core module
	Current monitor for 3V3_M2, VDDM_1V8, VDDM_1V1&OV6	INA3221	U76	0x41	SL1680 core module

4. Bringing Up the SL1680 Astra Machina System

4.1. Connecting External Components and Performing Hardware Testing

Perform the following steps to connect the external components to the SL1680 developer kit:

1. Connect a TypeC power supply to J213 (PWR_IN).
2. Connect TV to J12 (HDMI_Tx) with a HDMI cable.
3. Connect Network to J2 (RJ45) with an Ethernet cable.
4. Insert USB3.0 flash disk to J216 /J210 (USB3.0).
5. Insert USB2.0 flash disk to J215 (USB2.0) over TypeC/TypeA dongle.

If there are no short issues, power up the system and check voltages as shown in [Table 16](#), the LED status is shown in [Table 1](#).

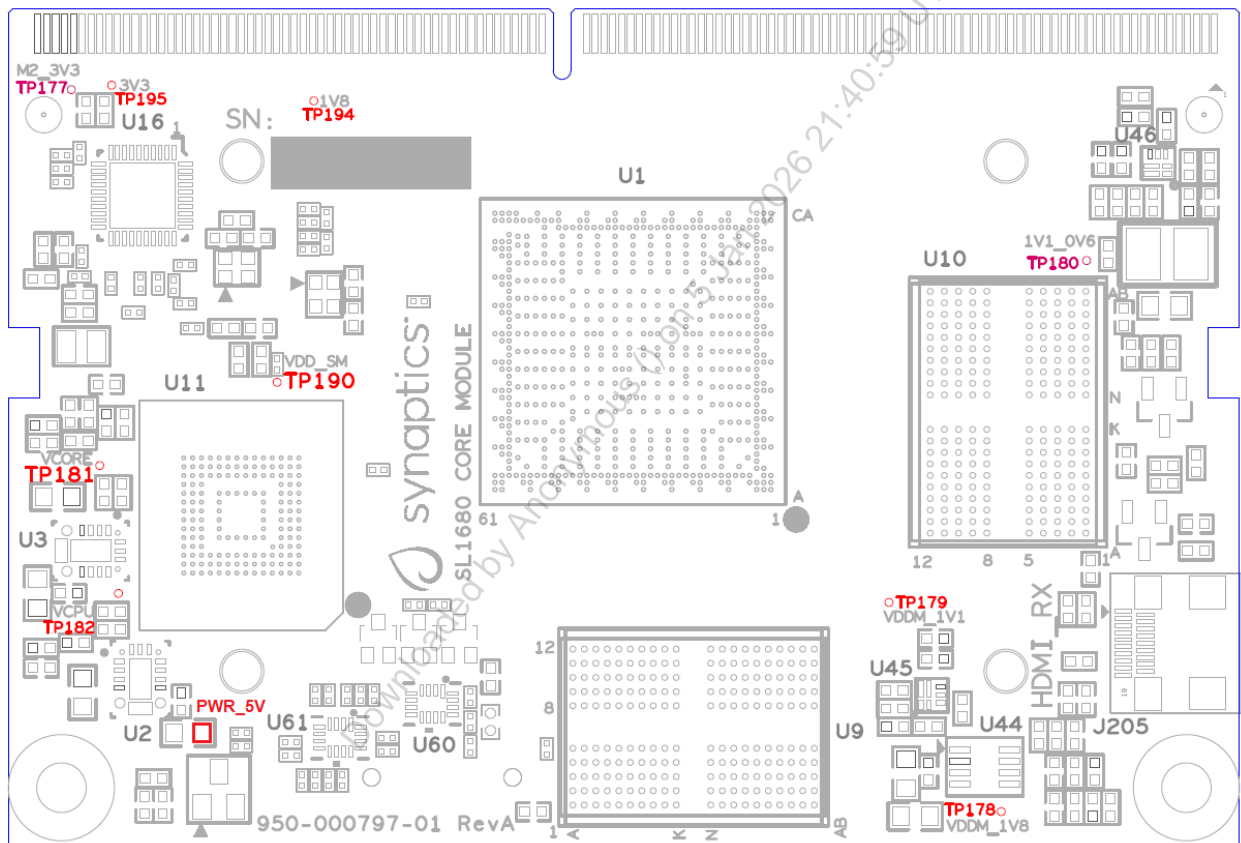













Figure 16. Short and voltage check points

Table 16. Short and voltage check points using any test point for ground

Ref Des	Form	Signal	Voltage
C1274	Right pad	PWR_5V	5.2V +/- 2% [5.096,5.304]
TP195	SMD pad	PWR_3V3	3.3V +/- 1% [3.267,3.333]
TP194	SMD pad	PWR_1V8	1.8V +/- 2% [1.764,1.836]
TP177	SMD pad	PWR_3V3-M2	3.3V +/- 1% [3.267,3.333]
TP178	SMD pad	PWR_VDDM_1V8	1.8V +/- 2% [1.764,1.836]
TP179	SMD pad	PWR_VDDM_1V1	1.1V +/- 2% [1.078,1.122]
TP180	SMD pad	PWR_VDDM_1V1&OV6	0.6V +/- 2% [0.588,0.612]
TP181	SMD pad	PWR_SoC_VCORE	0.8V +/- 2% [0.784,0.816]
TP182	SMD pad	PWR_SoC_VCPU	0.8V +/- 2% [0.784,0.816]
TP190	SMD pad	PWR_VDD_SM	0.8V +/- 2% [0.784,0.816]

5. Regulatory Compliance Certification

Region	EMC	RF	Safety	RoHS
CE(欧洲/Europe)				
FCC(美国/USA)	FCC logo is optional	CONTAINS FCC ID: RYK-WNFB265AXIBT (AP12275_M2P) ZQG-AP6611S (AP12611_M2)		
IC(加拿大/Canada)	CAN ICES-003(B)/NMB-003(B)	CONTAINS IC: 6158A-NFB265AXIBT (AP12275_M2P) 11956A-AP6611S (AP12611_M2)		
UKCA(英国/United Kingdom)				
BSMI(台湾/Taiwan)	 D33088 RoHS	 CCXXxxYYyyZzW NCC ID will be ready after NCC cert in AMPAK.		
PSE(日本/Japan)		020-200125 (AP12275_M2P)  R 217-241405 (AP12611_M2)		
CCC(中国/China)		CMIIT ID will be ready after SRRC cert in AMPAK.		
BIS(印度)				
KCC(韩国)				

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6. References

The following document is applicable to the SL1680 developer kit:

- *SL1680 Datasheet* (PN: 505-001413-01)
- *Astra Machina Foundation Series Quick Start Guide* (PN: 511-001404-01)
<https://github.com/synaptics-astra>

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7. Revision History

Last Modified	Revision	Description
April 3, 2024	A	Initial release.
May 8, 2024	B	Updated eMMC storage from “16GB” to “32GB” in 1.3.1 Features and Figure 3. SL1680 system block diagram , and some minor edits.
June 11, 2024	C	Updated the following: <ul style="list-style-type: none"> • Table 1. LED definitions on I/O board • Table 6. Hardware jumper settings definitions on I/O board • Figure 9. Locations of jumpers on the I/O board • Table 15. I2C bus descriptions
September 16, 2024	D	Added section 5 Regulatory Compliance Certification .
January 6, 2025	E	Updated Features bullet related to 4-pin POE+ connector.

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